

Divergence

- Define: *divergence* of \vec{F} at \mathcal{P} is the *flux density* at \mathcal{P} :

$$\operatorname{div} \vec{F}(\mathcal{P}) = \lim_{\substack{\Delta S \\ \text{"}\Delta D \rightarrow \mathcal{P}\text{"}}} \frac{\oiint \vec{F} \cdot d\vec{A}}{\Delta V}$$

- Compute: For $\vec{F} = P\hat{i} + Q\hat{j} + R\hat{k}$, have

$$\operatorname{div} \vec{F} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} = \vec{\nabla} \cdot \vec{F}.$$

- Interpret:

If \vec{F} is fluid flow velocity, can think of $\operatorname{div} \vec{F}$ in the following way: for a given point (x, y, z) , the number $\operatorname{div} \vec{F}(x, y, z)$ gives the rate at which fluid is being injected into the flow at that point.

Divergence Theorem

$$\begin{aligned}\iiint_D \vec{\nabla} \cdot \vec{F} dV &= \iiint_D \frac{\oiint_{\Delta S} \vec{F} \cdot d\vec{A}}{dV} dV \\ &= \iiint_D \frac{\text{flux through surface of} \\ &\quad \text{infinitesimal piece of } D}{dV} dV \\ &= \iiint_D \text{flux through surface of} \\ &\quad \text{infinitesimal piece of } D \\ &= \text{flux through surface of } D \\ &= \oiint_S \vec{F} \cdot d\vec{A}\end{aligned}$$

Curl

- Define: \hat{n} -component of *curl* of \vec{F} at \mathcal{P} is the *circulation density* at \mathcal{P} :

$$(\text{curl } \vec{F}) \cdot \hat{n} = \lim_{\substack{\Delta C \rightarrow \mathcal{P} \\ \Delta A}} \frac{\oint \vec{F} \cdot d\vec{r}}{\Delta A}$$

- Compute: For $\vec{F} = P\hat{i} + Q\hat{j} + R\hat{k}$, have

$$\text{curl } \vec{F} = \left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \hat{i} + \left(\frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) \hat{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \hat{k} = \vec{\nabla} \times \vec{F}.$$

- Interpret:

If \vec{F} is fluid flow velocity, can think of $\text{curl } \vec{F}$ in the following way: for a given point (x, y, z) , the direction of the vector $\text{curl } \vec{F}(x, y, z)$ is the direction in which to orient an infinitesimal paddlewheel to get the fastest rotation rate and the magnitude of $\text{curl } \vec{F}(x, y, z)$ is proportional to that rotation rate.

Stokes' Theorem

$$\begin{aligned}\iint_S (\vec{\nabla} \times \vec{F}) \cdot d\vec{A} &= \iint_S (\vec{\nabla} \times \vec{F}) \cdot \hat{n} dA \\ &= \iint_S \frac{\oint \vec{F} \cdot d\vec{r}}{dA} dA \\ &= \iint_S \frac{\text{circulation around edge of} \\ &\quad \text{infinitesimal piece of } S}{dA} dA \\ &= \iint_S \text{circulation around edge of} \\ &\quad \text{infinitesimal piece of } S \\ &= \text{circulation around edge of } S \\ &= \oint_C \vec{F} \cdot d\vec{r}\end{aligned}$$