

### Fundamental theorems of calculus

Note: In each of the following theorems, hypotheses on continuity of the integrand and “niceness” of the relevant region are omitted in order to focus on other details.

#### Fundamental Theorem for Definite Integrals

If  $F'(x) = f(x)$ , then  $\int_a^b f(x) dx = F(b) - F(a)$ .

By substituting, we can also write the conclusion as

$$\int_a^b F'(x) dx = F(b) - F(a).$$

#### Fundamental Theorem for Line Integrals

Let  $C$  be a curve that starts at  $A$  and ends at  $B$ . If  $\vec{\nabla}V = \vec{F}$ , then

$$\int_C \vec{F} \cdot d\vec{r} = V(B) - V(A).$$

By substituting, we can also write the conclusion as

$$\int_C \vec{\nabla}V \cdot d\vec{r} = V(B) - V(A).$$

#### Divergence Theorem

Let  $D$  be a solid region with the closed surface  $S$  as the edge of  $D$  and area element vectors  $d\vec{A}$  for  $S$  oriented outward. If  $\vec{\nabla} \cdot \vec{F} = f$ , then

$$\iiint_D f dV = \oiint_S \vec{F} \cdot d\vec{A}.$$

By substituting, we can also write the conclusion as

$$\iiint_D (\vec{\nabla} \cdot \vec{F}) dV = \oiint_S \vec{F} \cdot d\vec{A}.$$

#### Stokes' Theorem

Let  $S$  be a surface with the closed curve  $C$  as the edge of  $S$ . Orient the area element vectors  $d\vec{A}$  and the curve  $C$  to have a right-hand relation. If  $\vec{\nabla} \times \vec{F} = \vec{G}$ , then

$$\iint_S \vec{G} \cdot d\vec{A} = \oint_C \vec{F} \cdot d\vec{r}.$$

By substituting, we can also write the conclusion as

$$\iint_S (\vec{\nabla} \times \vec{F}) \cdot d\vec{A} = \oint_C \vec{F} \cdot d\vec{r}.$$

### Green's Theorem

We can derive Green's Theorem as a special case of Stokes' Theorem. Consider a vector field of the form  $\vec{F} = P(x, y)\hat{i} + Q(x, y)\hat{j} + 0\hat{k}$ . Note that the curl of  $\vec{F}$  is

$$\vec{\nabla} \times \vec{F} = (0 - 0)\hat{i} - (0 - 0)\hat{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}\right)\hat{k} = \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}\right)\hat{k}.$$

Let  $D$  be a planar region in the  $xy$ -plane with the closed curve  $C$  as the edge of  $D$ . Orient the curve  $C$  counterclockwise. If we think of  $D$  as a surface, we can express the area element vectors as  $d\vec{A} = dx dy \hat{k}$ .

We now compute

$$(\vec{\nabla} \times \vec{F}) \cdot d\vec{A} = \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}\right)\hat{k} \cdot dx dy \hat{k} = \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}\right) dx dy.$$

Using this special case in the conclusion of Stokes' Theorem, we get

$$\iint_D \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}\right) dx dy = \oint_C (P\hat{i} + Q\hat{j}) \cdot d\vec{r}.$$

Using an alternate notation for line integrals, this can also be written as

$$\boxed{\iint_D \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}\right) dx dy = \oint_C P dx + Q dy.}$$

### Common structure among these fundamental theorems

The theorems given above all have the same all of which have the same basic structure: *Integrating the derivative of a function over a region gives the same value as integrating the function itself over the edge of the region.* In the case of a one-dimensional region such as a curve, the edge consists of only two points so integrating over the edge reduces to simply adding together two values. Here's how this basic idea plays out in the specific cases:

- In the Fundamental Theorem for Definite Integrals, the region is an interval  $[a, b]$  on the input axis so the edge of the region consists of two points  $a$  and  $b$  on the axis. The function is a function of one variable and the derivative is the first kind of derivative you learned about. In words, the theorem says that integrating the derivative  $F'$  over the interval  $[a, b]$  is the same as adding up the function  $F$  for the two endpoints. But wait, isn't  $F(b) - F(a)$  a difference rather than a sum? Yes, but we can think of it as  $(-1)F(a) + F(b)$ . The factor of  $-1$  relates to the issue of orientation. At  $a$ , the direction pointing out is the negative direction while at  $b$ , the outward pointing direction is the positive direction. The factor of  $-1$  reflects the fact that the outward direction at  $a$  is the negative direction.
- In the Fundamental Theorem for Line Integrals, the region is a curve  $C$  so the edge consists of two points  $A$  and  $B$  or on the plane or in space. The function is a function of two or more variable and the derivative is the gradient. In

words, the theorem says that integrating the gradient  $\vec{\nabla}V$  over the curve  $C$  is the same as adding up the function  $V$  for the two endpoints. We usually write this as  $V(B) - V(A)$  but can think of it as  $(-1)V(a) + V(b)$ . As above, the factor of  $-1$  relates to the issue of orientation and is related to the fact that  $d\vec{r}$  points into the curve at  $A$  and out of the curve at  $B$ .

- In Green's Theorem, the region is a planar region  $D$  with edge consisting of a closed curve  $C$ . The function is a planar vector field and the derivative is the  $\hat{k}$  component of the curl (which is the only non-zero component of the curl for a planar vector field). In words, the theorem says that integrating the curl  $\partial Q/\partial x - \partial P/\partial y$  over the region  $D$  is the same as integrating the vector field  $P\hat{i} + Q\hat{j}$  over the curve  $C$ .
- In Stoke's Theorem, the region is a surface  $S$  in space with edge consisting of a closed curve  $C$ . The function is a vector field and the derivative is the curl. In words, the theorem says that integrating the curl  $\vec{\nabla} \times \vec{F}$  over the surface  $S$  is the same as integrating the vector field  $\vec{F}$  over the curve  $C$ .
- In the Divergence Theorem, the region is a solid region in space with edge consisting of a closed surface  $S$ . The function is a vector field and the derivative is the divergence. In words, the theorem says that integrating the divergence  $\vec{\nabla} \cdot \vec{F}$  over the solid region  $D$  is the same as integrating the vector field  $\vec{F}$  over the surface  $S$ .

We can also organize these in terms of the dimension of the region and its edge:

- In the Fundamental Theorems for Definite Integrals and Line Integrals, the region is one-dimensional (an interval or a curve) and the edge is zero-dimensional (a set of two points).
- In Green's Theorem and Stoke's Theorem, the region is two-dimensional (a planar region or a surface) and the edge is one-dimensional (a curve).
- In the Divergence Theorem, the region is three-dimensional (a solid region) and the edge is two-dimensional (a surface).

### Importance of the fundamental theorems

The fundamental theorems are important for both aesthetic value and as useful tools. Aesthetically, the fundamental theorems provide a beautiful unity among the various types of function, derivative, and integral we have explored in calculus. As tools, we use the fundamental theorems in two primary ways:

- Rather than evaluate an integral directly, we can trade it in for a related expression that is easier to evaluate. You are very familiar with doing this when you trade in a definite integral  $\int_a^b f(x) dx$  for the sum  $(-1)F(a) + F(b) = F(b) - F(a)$ . Problems 1, 3, and 4 give you practice with this type of "trading in" using the other fundamental theorems.
- Given information about the derivative of a function at each point in a region, we can deduce information about certain integrals for the function itself (and vice versa). Problem 2 gives you an example of this use.

### Problems: Fundamental theorems of calculus

1. Use the Divergence Theorem to evaluate  $\oiint_S \vec{F} \cdot d\vec{A}$  where

$$\vec{F} = (z - x)\hat{i} + (x - y)\hat{j} + (y - z)\hat{k}$$

and  $S$  is the sphere of radius 4 centered at the origin with  $d\vec{A}$  oriented outward.

$$\text{Answer: } \oiint_S \vec{F} \cdot d\vec{A} = -256\pi$$

2. Suppose that  $\vec{F}$  is a vector field with  $\vec{\nabla} \cdot \vec{F} = 0$  for all points in  $\mathbb{R}^3$ . Show that  $\oiint_S \vec{F} \cdot d\vec{A} = 0$  for any closed surface  $S$  in  $\mathbb{R}^3$ .

3. Use Stokes' Theorem (or Green's Theorem) to evaluate  $\oint_C \vec{F} \cdot d\vec{r}$  where

$\vec{F} = y^2\hat{i} - x^2\hat{j}$  and  $C$  is the square in the  $xy$ -plane with corners at  $(0,0)$ ,  $(1,0)$ ,  $(1,1)$ , and  $(0,1)$  traversed counterclockwise.

$$\text{Answer: } \oint_C \vec{F} \cdot d\vec{r} = -2$$

4. Suppose  $C$  is a simple closed curve in the  $xy$ -plane. Let  $\vec{F} = -y\hat{i} + x\hat{j}$  and consider the line integral  $\oint_C \vec{F} \cdot d\vec{r}$ . Use Stokes' Theorem (or Green's Theorem) to relate the value of this line integral to the area of the region enclosed by  $C$ . Note: A *simple* curve is one with no self-intersections so a simple closed curve is a loop with no self-intersections.

5. Use your result from Problem 4 to compute the area enclosed by the ellipse  $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$ .